Rumps

About me

- Over caffeinated wolf
- Voiding warranties for a living since 2018
- Projects :
  - Done :
    - Bypassing the Hantek DSO software limitation
    - GPS spoofing on DJI Inspire 1
    - Recovering and exploiting IP cameras
  - WIP :
    - Freeway toll gate token reverse engineering
    - NOVAL 4G IoT xxxxx 😉

Twitter / X : @CyberWolf_2077

Blog : whiterose-infosec.super.site/

What this talk is about

- Understanding how companies produces electronic devices
- Checking basic elements on your devices to gain access and add functionalities
- Fucking things up (a lot)

What this talk isn't about

- Motivating you to do so on all your devices 😉

Story 1: Hantek DSO

- Introduction
- Open the oscilloscope
- Finding the serial pins
- Connect the USB / UART
- Edit the config file
- Apply the edit
- Checking the modification

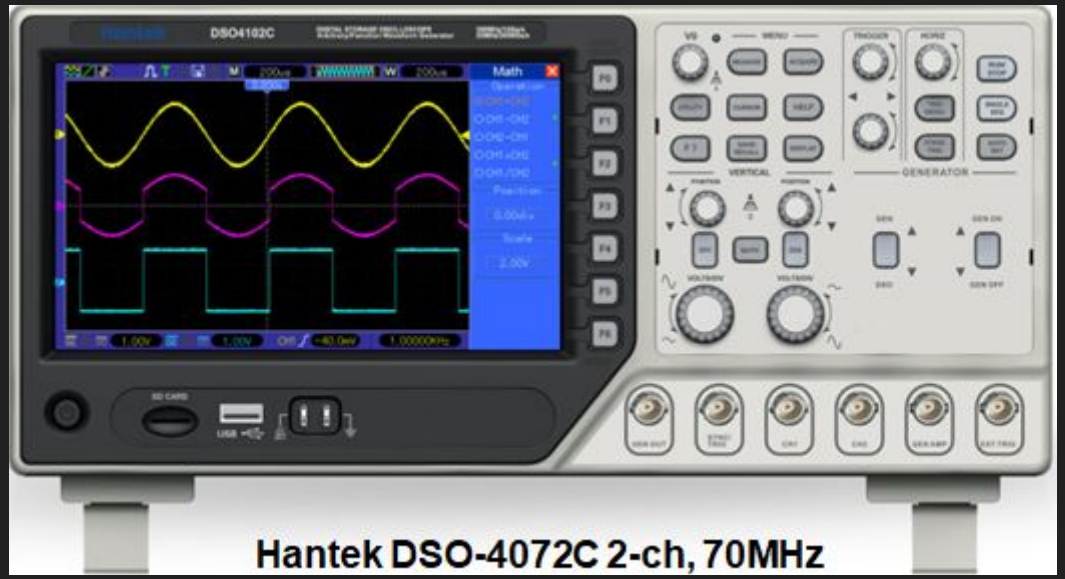
Story 2: Flying anywhere

- Introduction
- Getting to simulate a GPS constellation
- Time to create our fake constellation
- Ready to take off
- Let’s travel around the world !
- Time to do some sketchy shit
- Not fun issue on the DJI app
- Fun side effects

Why pay 500$ a device when you can get the same out of the 250$ version

How Hantek (and others) tries to same money but could lose a lot

Introduction



Hantek DSO-4072C 2-ch, 70MHz

Open the oscilloscope

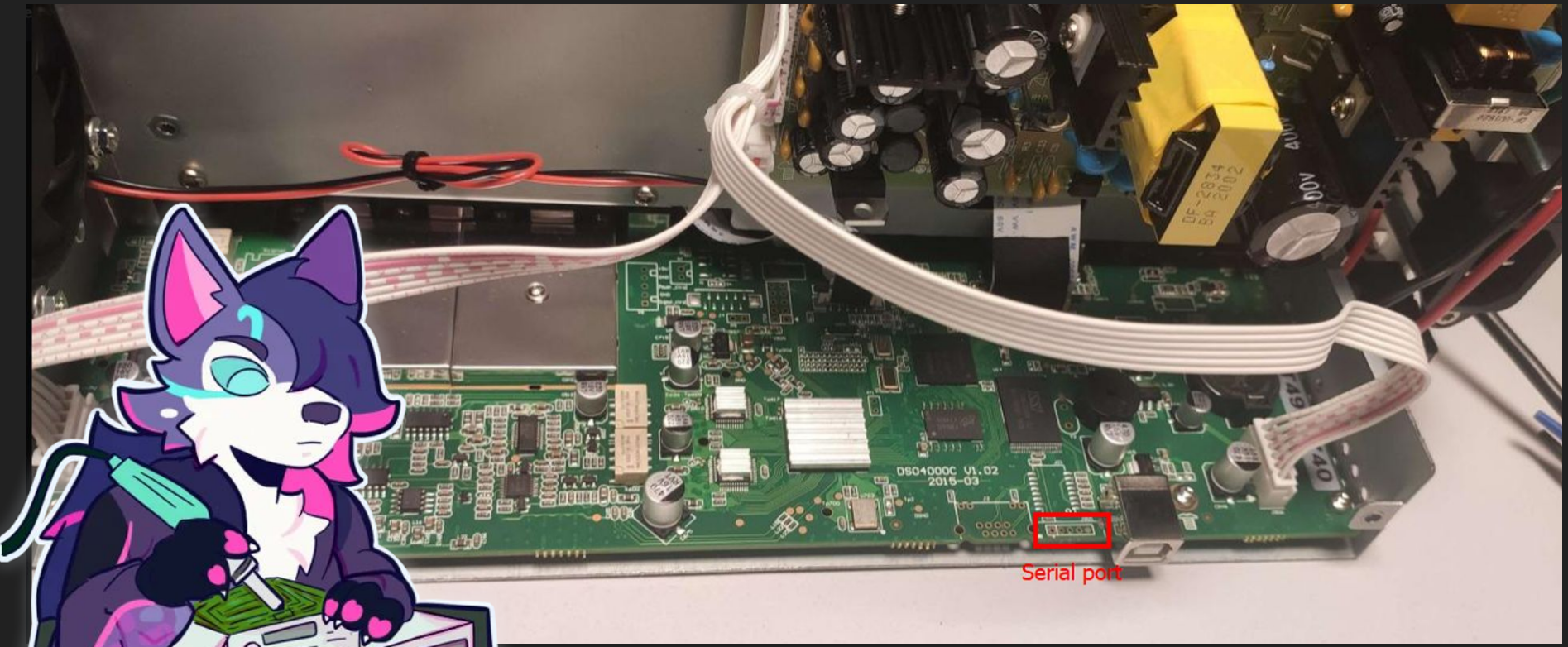
⚠ This is not a tutorial

Open the oscilloscope

⚠ This is not a tutorial

Finding the serial pins

⚠ This is not a tutorial



Finding the serial pins

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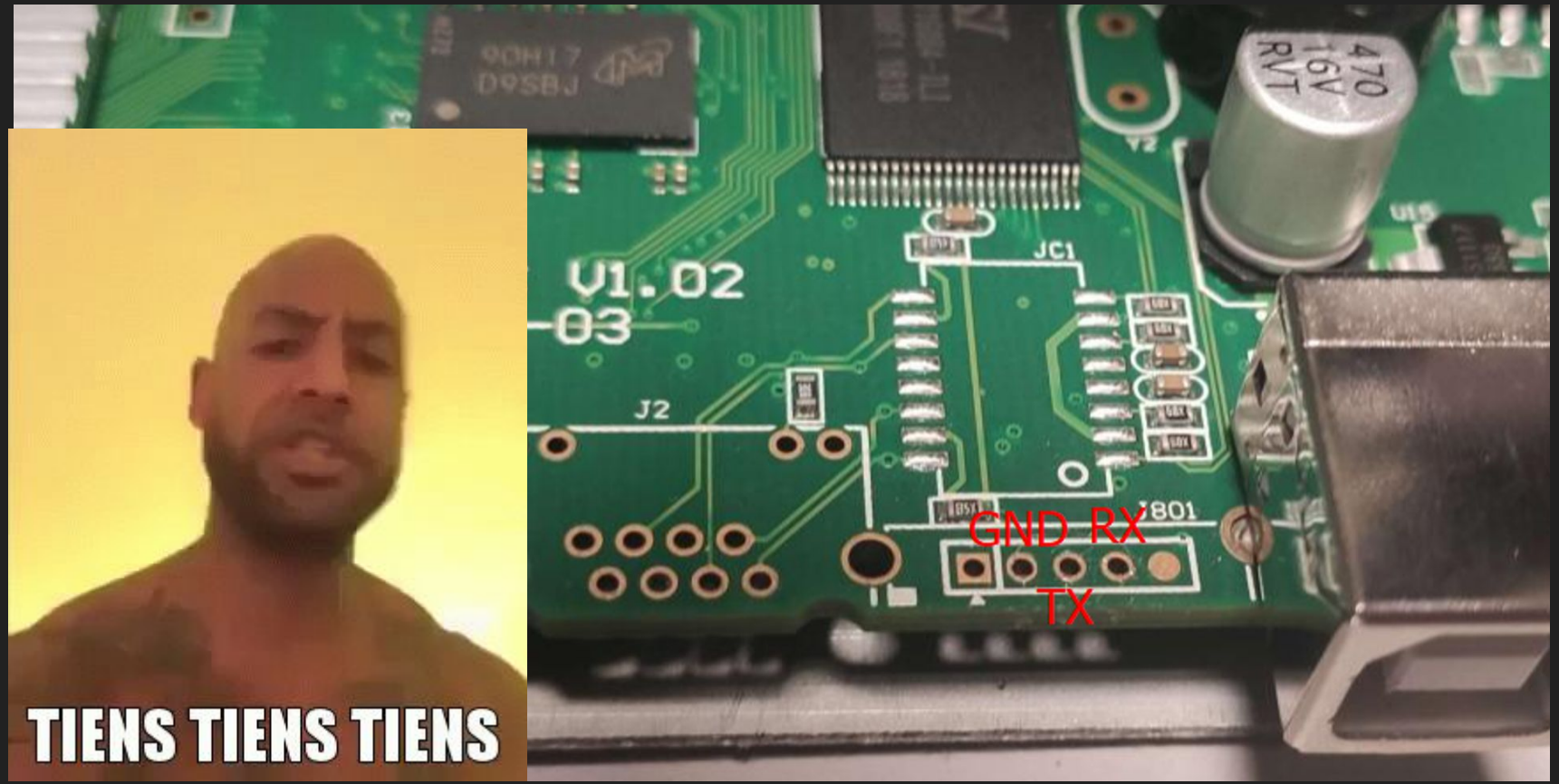

Connect the USB / UART

⚠ This is not a tutorial

```
Speed (Bps) : 115200
Data bytes  : 8
Stop bits   : 1
Parity      : none
```

```
--------------------------------------------------------------------------------
start
--------------------------------------------------------------------------------
make snd node.

Erasing 128 Kibyte @ 80000 - 100% complete..
mtd3: 00080000 00020000 "misc"
Erasing 128 Kibyte @ 80000 - 100% complete.
<0>open /dev/adc: No such file or directory
*****set_value = 1
param_array[70] = 1
SetFpgaCh1VerticDac:value=25095
value1 = 14424
value2 = 14424
SetFpgaCh1VerticDac:value=25095
value1 = 14424
value2 = 14424
[root@Hantek ~]#
```

Edit the config file and Applying the edit

⚠ This is not a tutorial

```
# Create a local backup of the config file
cp i2c.log i2c.log.bkp
```

```
vi i2c.log
# Edit the line [bw]
[bw] 70 to [bw] 200
```

```
reboot
```

Checking the modification

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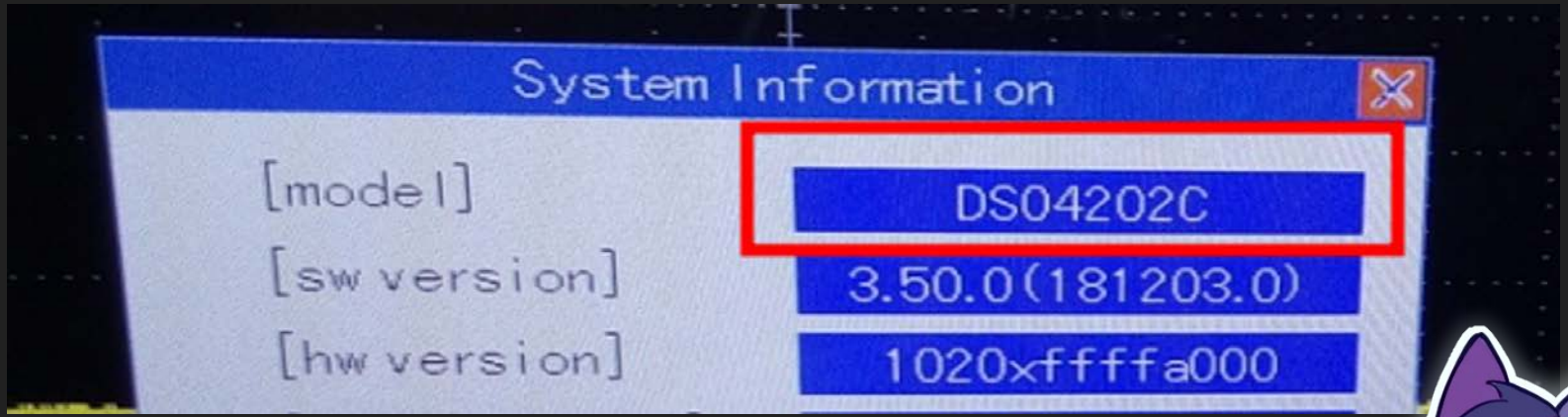
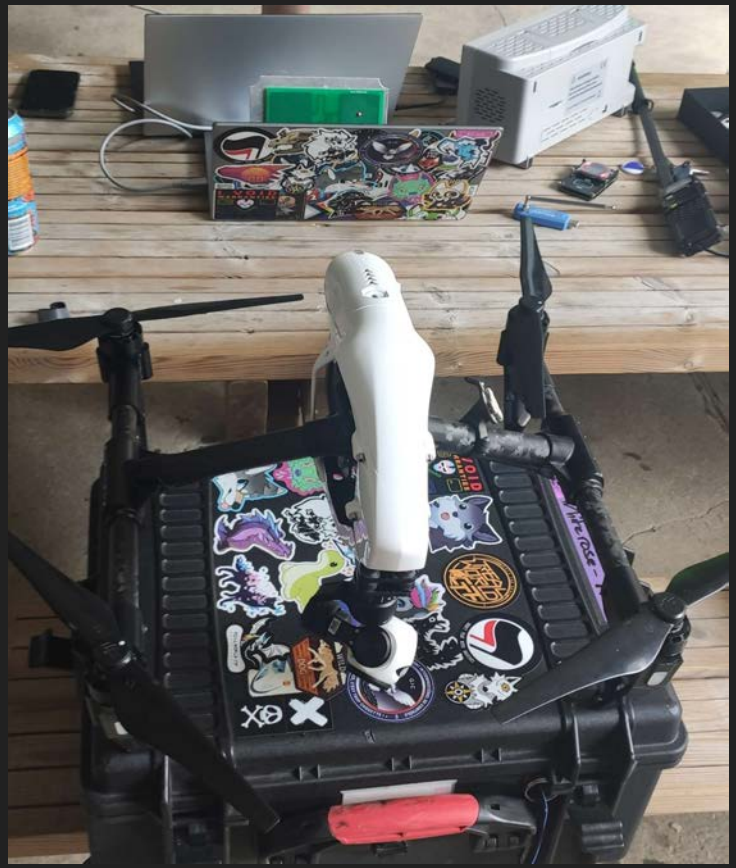


Hantek DSO-4202C : 200MHz

Could your drone fly anywhere in the world ?

Introduction



Getting to simulate a GPS constellation

⚠ This is not a tutorial

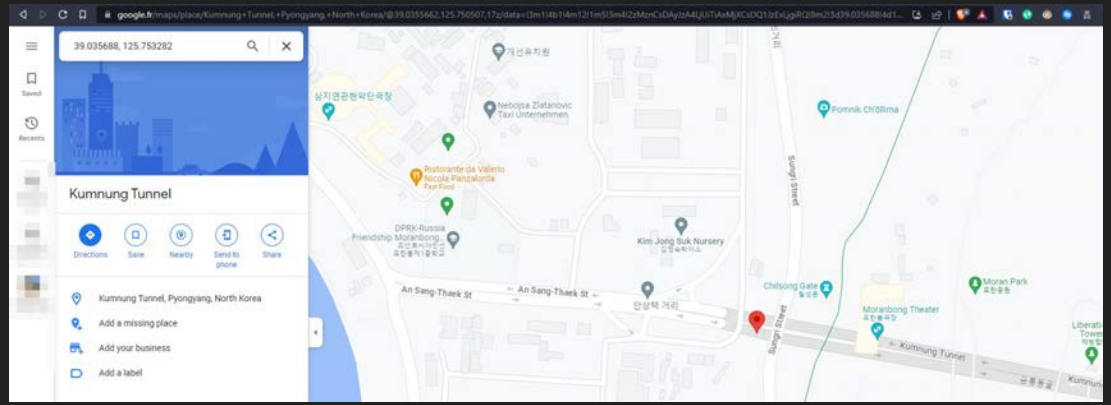
```
┌──(kali㉿kali)-[~/GPS_SPOOF/gps-sdr-sim]
└─$ sudo apt install hackrf
┌──(kali㉿kali)-[~/GPS_SPOOF/gps-sdr-sim]
└─$ sudo hackrf_info
```

```
┌──(kali㉿kali)-[~]
└─$ sudo hackrf_info
[sudo] password for kali:
hackrf_info version: 2022.09.1
libhackrf version: 2022.09.1 (0.7)
Found HackRF
Index: 0
Serial number: 0000000000000000f75461dc285537c3
hackrf_open() failed: Resource busy (-1000)
```

```
┌──(kali㉿kali)-[~/GPS_SPOOF/gps-sdr-sim]
└─$ mkdir GPS_SPOOF
┌──(kali㉿kali)-[~/GPS_SPOOF/gps-sdr-sim]
└─$ cd GPS_SPOOF
┌──(kali㉿kali)-[~/GPS_SPOOF/gps-sdr-sim]
└─$ sudo git clone https://github.com/osqzss/gps-sdr-sim.git
┌──(kali㉿kali)-[~/GPS_SPOOF/gps-sdr-sim]
└─$ cd gps-sdr-sim
┌──(kali㉿kali)-[~/GPS_SPOOF/gps-sdr-sim]
└─$ sudo gcc gpssim.c -lm -O3 -o gps-sdr-sim -DUSER_MOTION_SI
ZE=4000
```

Time to create our fake constellation

⚠ This is not a tutorial



Time to create our fake constellation

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```
┌──(kali㉿kali)-[~/GPS_SPOOF/gps-sdr-sim]
└─$ sudo ./gps-sdr-sim -b 8 -e ../../Desktop/brdc1450.23n -l "39.035688, 125.753282, 100"
```

```
┌──(kali㉿kali)-[~/GPS_SPOOF/gps-sdr-sim]
└─$ sudo ./gps-sdr-sim -b 8 -e ../../Desktop/brdc1450.23n -l "39.035688, 125.753282, 100"
Using static location mode.
xyz =  -2898641.1,   4025980.0,   3995458.2
llh =    39.035688,  125.753282,     100.0
Start time = 2023/05/25,00:00:00 (2263:345600)
Duration = 400.0 [sec]
02  111.3  61.1  21003548.6   5.9
04  209.3   4.4  25226098.3  14.5
07  293.3  53.3  21363959.4   6.1
08  350.2  77.2  20171628.4   5.3
09  238.6  11.6  24505077.1  12.2
10   78.4   5.9  25363791.7  17.4
14  291.5   0.9  25767857.9  13.0
16   91.3  32.5  22668949.9   9.2
21  170.3  46.5  21127679.8   6.9
23   46.7   2.9  25531398.1  17.4
26  108.5   5.2  25408402.8  18.0
27   46.6  46.5  21394511.3   7.0
30  313.2  24.6  23364763.8   9.5
Time into run = 173.1^C
```

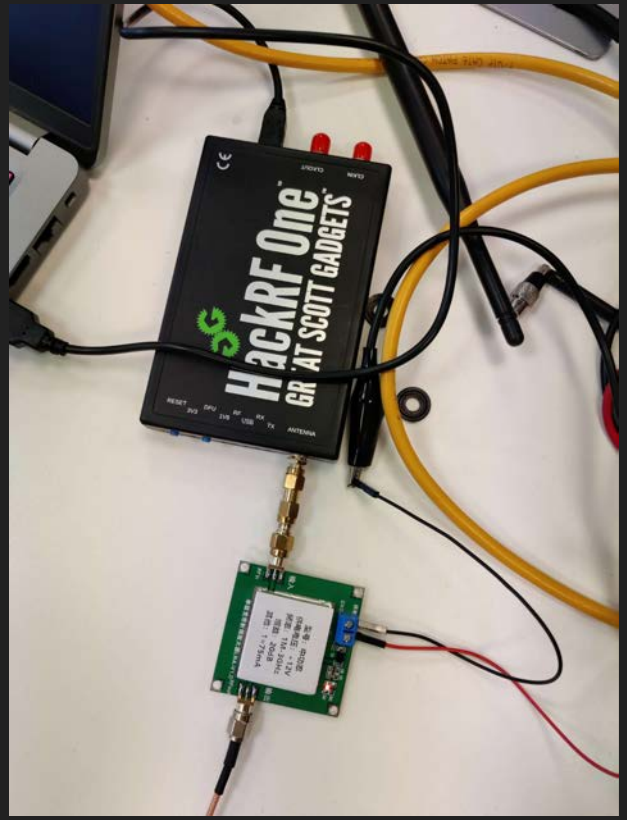
⚠ This is not a tutorial

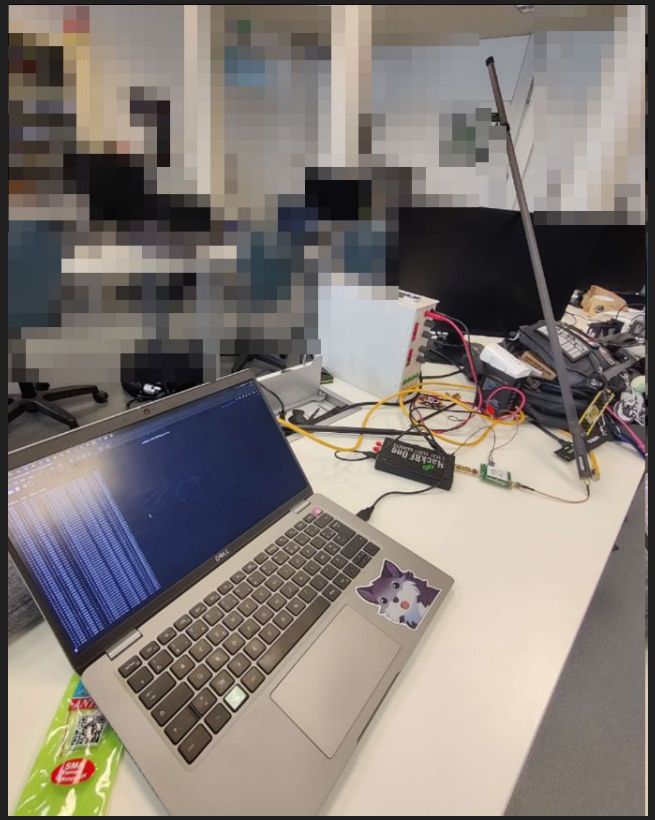
Ready to take off (maybe)

```
┌──(kali㉿kali)-[~/GPS_SPOOF/gps-sdr-sim]
└─$ sudo hackrf_transfer -t gpssim.bin -f 1575420000 -s 2600000 -a 1 -x 0
```

⚠ This is not a tutorial

Ready to take off (for sure)





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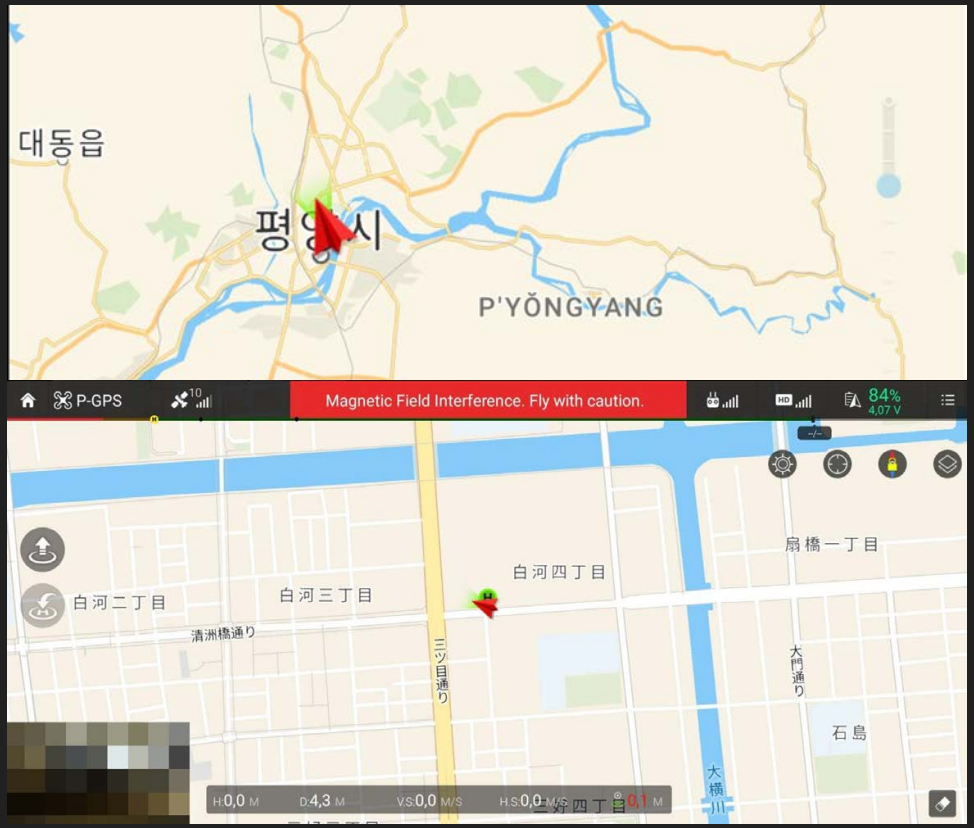
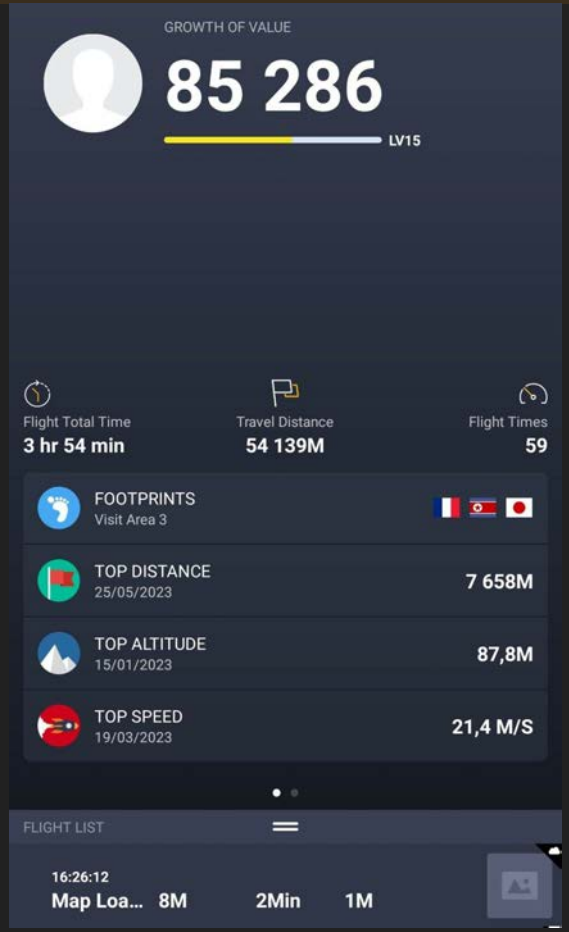
Let’s travel around the world !





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Let’s travel around the world !

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Let’s travel around the world !

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Time to do some sketchy shit

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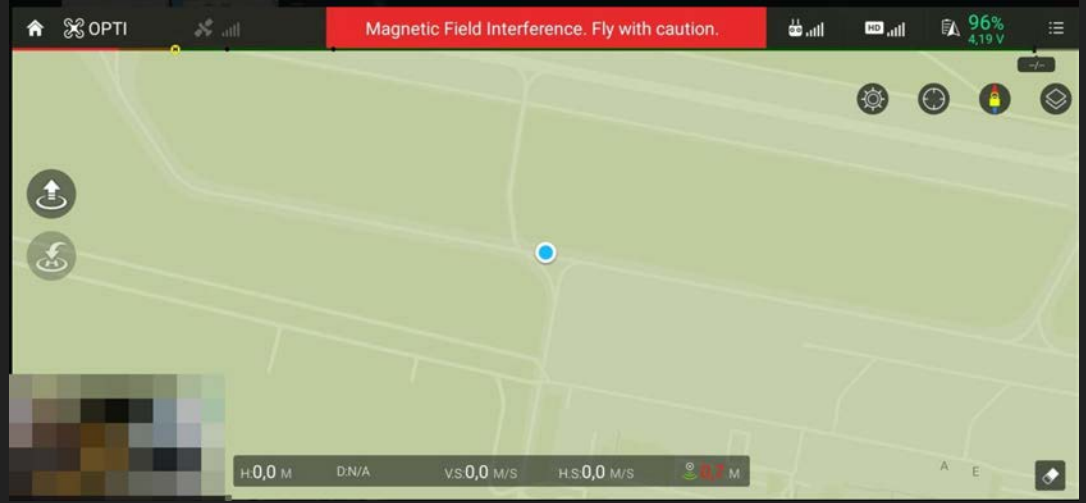
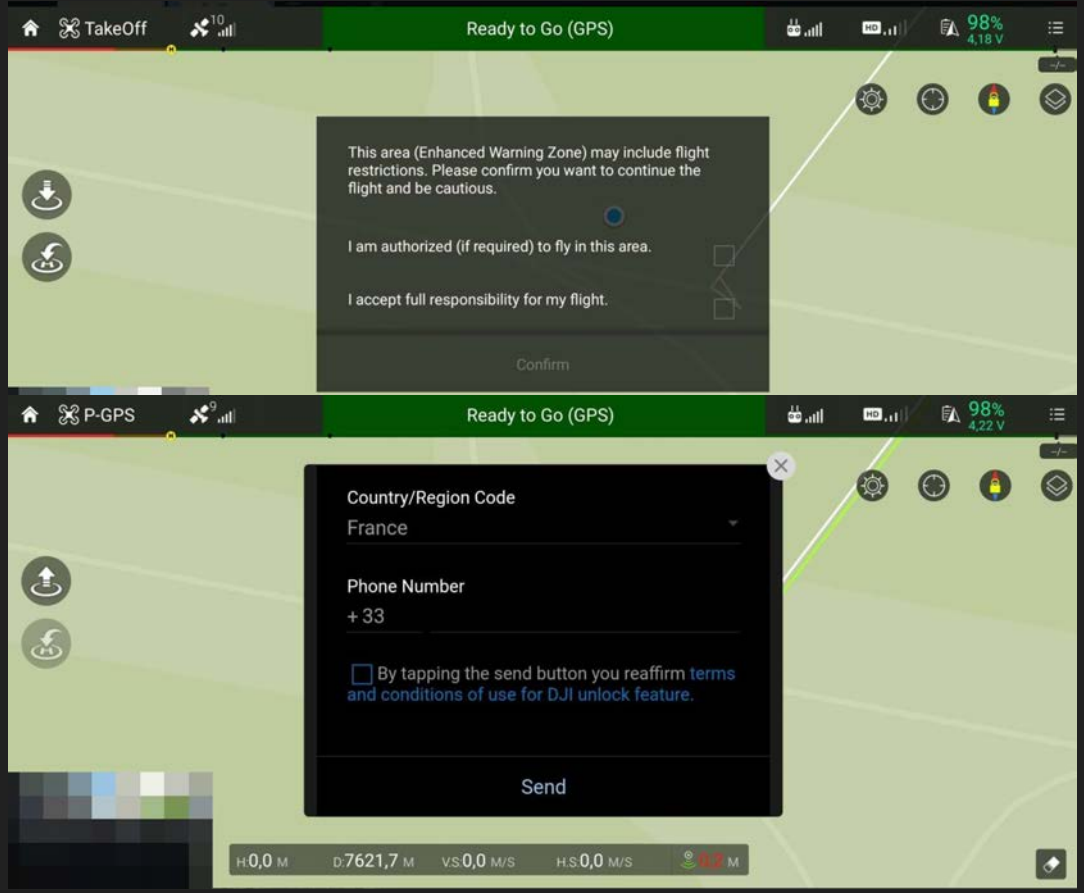
Time to do some sketchy shit



Not fun issue on the DJI app



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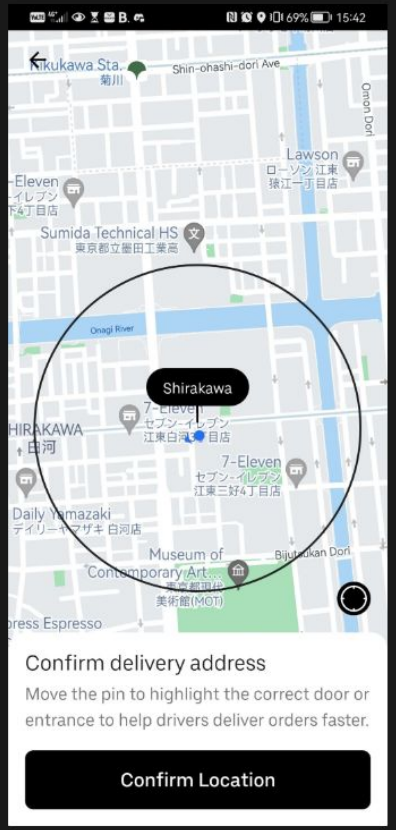
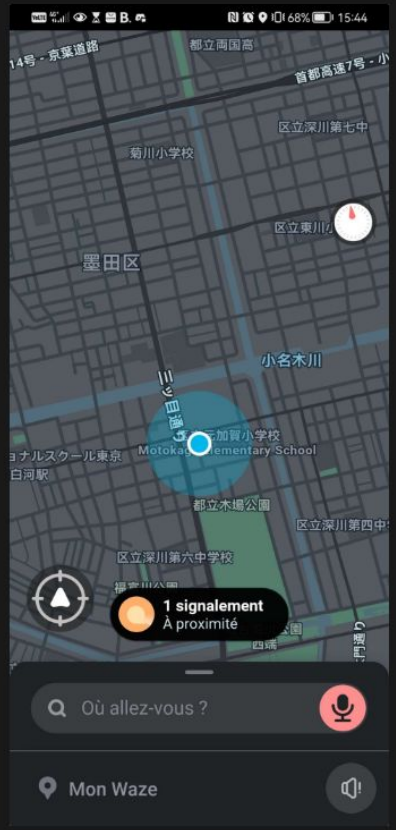
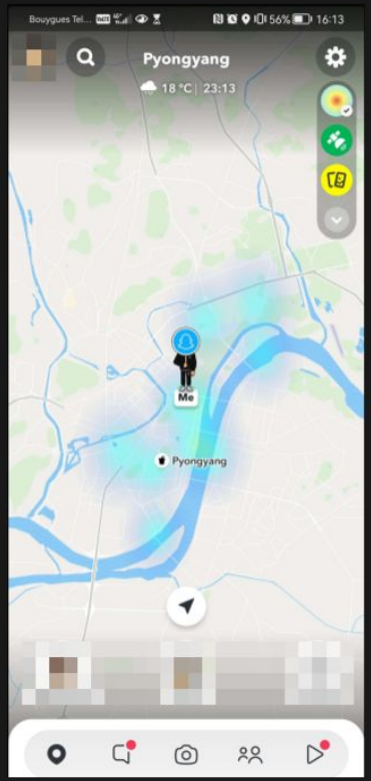
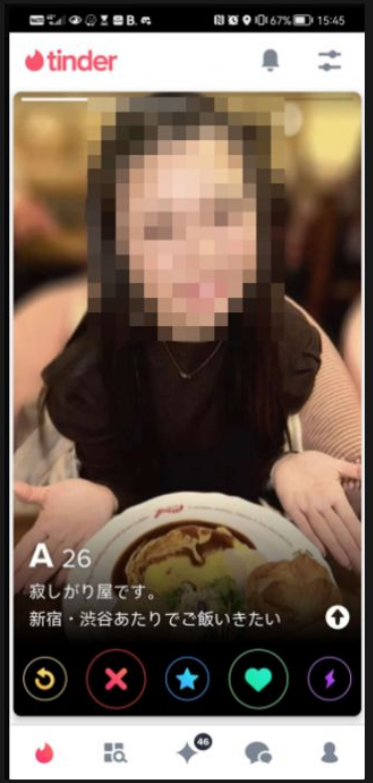
Fun side effects









Hantek DSO

- https://github.com/WiZZteXX/DSO4xx4c/blob/i2c-tools/Hacking%20the%20HANTEK%20DSO4xx4BC.pdf
- https://www.eevblog.com/forum/testgear/hantek-tekway-dso-hack-get-200mhz-bw-for-free/
- https://www.eevblog.com/forum/testgear/upgrading-the-hantek-dso4072c-osciloscope-bandwidth-from-70mhz-to-200mhz/
-

DJI spoofing

- https://github.com/osqzss/gps-sdr-sim
- https://cddis.nasa.gov/archive/gnss/data/daily/
-

Questions